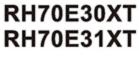
# **ALIGN**

TREX 700L V2 INSTRUCTION MANUAL

使用說明書





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無刷調速器使用說明 FLIGHT ADJUSTMENT AND SETTING

飛行動作調整與設定

TROUBLESHOOTING 飛行中狀況排除





Thank you for purchasing of Align products. Please read the manual carefully before installing and be sure to retain the manual for future reference. Specifications, contents of parts and availability are subject to change, ALIGN RC is not responsible for inadvertent errors in this publications.

承蒙閣下選用亞拓遙控世界系列產品, 謹表謝意。使用前, 請務必詳閱本說明書, 相信一定能夠給您帶來相當大的幫助, 也請您妥善保管這本說明書, 以做為日後參考。本公司將不對此印刷物之異動負責, 也無法主動通知消費者任何更新或異動。本說明書內記載的材質、規格或零件包裝之內容物如有異動, 請依亞拓官網公告為主。

# 1.INTRODUCTION 前言



Thank you for buying ALIGN Products. The T-REX 700L V2 Helicopter is designed as an easy to use, full featured Helicopter R/C model capable of all forms of rotary flight. Please read the manual carefully before assembling the model, and follow all precautions and recommendations located within the manual. Be sure to retain the manual for future reference, routine maintenance, and tuning. The T-REX 700L V2 is a new product developed by ALIGN. It features the best design available on the Micro-Heli market to date, providing flying stability for beginners, full aerobatic capability for advanced fliers, and unsurpassed reliability for customer support.

感謝您選購亞拓產品,為了讓您容易方便的使用 T-REX 700L V2 直昇機、請您詳細的閱讀完這本說明書之後再進行組裝以及操作這台直昇機,同時請您妥善的保存這本說明書、作為日後進行調整以及維修的参考。T-REX 700L V2 是由亞拓自行研發的新產品,不論您是需求飛行穩定性的初學者或是追求性能的飛行愛好者。T-REX 700L V2 將是您最佳的選擇。

# WARNING LABEL LEGEND 標誌代表涵義

○ FORBIDDEN 禁止 Do not attempt under any circumstances.

在任何禁止的環境下,請勿嘗試操作。

**AWARNING** 警告 Mishandling due to failure to follow these instructions may result in damage or injury.

因為疏忽這些操作說明,而使用錯誤可能造成財產損失或嚴重傷害。

**企AUTION** 注意 Mishandling due to failure to follow these instructions may result in danger. 因為疏忽這些操作說明,而使用錯誤可能造成危險。

# IMPORTANT NOTES 重要聲明

R/C helicopters, including the T-REX 700L V2 are not toys. R/C helicopter utilize various high-tech products and technologies to provide superior performance. Improper use of this product can result in serious injury or even death. Please read this manual carefully before using and make sure to be conscious of your own personal safety and the safety of others and your environment when operating all ALIGN products. Manufacturer and seller assume no liability for the operation or the use of this product. This product is intended for use only by adults with experience flying remote control helicopters at a legal flying field. After the sale of this product we cannot maintain any control over its operation or usage.

As the user of this product, you are solely responsible for operating it in a manner that does not endanger yourself and others or result in damage to the product or the property of others.

T-REX 700L V2 遙控直昇機並非玩具,它是結合了許多高科技產品所設計出來的休閒用品,所以商品的使用不當或不熟悉都可能會造成嚴重傷害甚至死亡,使用之前請務必詳讀本說明書,勿輕忽並注意自身安全。注意!任何遙控直昇機的使用,製造商和經銷商是無法對使用者於零件使用的損耗異常或組裝不當所發生之意外負任何責任,本產品是提供給有操作過模型直昇機經驗的成人或有相當技術的人員在旁指導於當地合法遙控飛行場飛行,以確保安全無處下操作使用,產品售出後本公司將不負任何操作和使用控制上的任何性能與安全責任。

做為本產品的使用者,您,是唯一對於您自己操作的環境及行為負全部的責任之人。

We recommend that you obtain the assistance of an experienced pilot before attempting to fly our products for the first time. A local expert is the best way to properly assemble, setup, and fly your model for the first time. The T-REX 700L requires a certain degree of skill to operate, and is a consumer item. Any damage or dissatisfaction as a result of accidents or modifications are not covered by any warrantee and cannot be returned for repair or replacement. Please contact our distributors for free technical consultation and parts at discounted rates when you experience problems during operation or maintenance. As Align Corporation Limited has no control over use, setup, final assembly, modification or misuse, no liability shall be assumed nor accepted for any resulting damage or injury. By the act of use, setup or assembly, the user accepts all resulting liability.

模型商品屬於需高操作技術且為消耗性之商品,如經拆裝使用後,會造成不等情況零件損耗,任何使用情況所造成商品不良或不滿意,將無法於保固條件內更換 新品或退貨,如遇有使用操作維修問題,本公司全省分公司或代理商將提供技術指導、特價零件供應服務。對使用者的不當使用、設定、組裝、修改、或操作不 良所造成的破損或傷害,本公司無法控制及負責。任何使用、設定、組裝、修改、或操作不良所造成的破損、意外或傷害,使用者應承擔全部責任。

# 2.SAFETY NOTES 安全注意事項

ALIGN



- Fly only in safe areas, away from other people. Do not operate R/C aircraft within the vicinity of homes or crowds of people. R/C aircraft are prone to accidents, failures, and crashes due to a variety of reasons including, lack of maintenance, pilot error, and radio interference. Pilots are responsible for their actions and damage or injury occurring during the operation or as of a result of R/C aircraft models.
- · Prior to every flight, carefully check rotorhead spindle shaft screws and tall blade grip screws, linkage balls and screws, ensure they are firmly secured.
- 遙控模型飛機、直昇機關高危險性商品,飛行時務必遠離人群,人為組裝不當或機件損壞、電子控制設備不良,以及操控上的不熟悉、都有可能導致飛行失控 損傷等不可預期的意外,請飛行者務必注意飛行安全,並需了解自負疏忽所造成任何意外之責任。
- · 每題飛行前須仔細檢查, 主旋翼夾座橫輪螺絲、尾旋翼夾座螺絲, 以及機身各部位球頭、螺絲, 確實上膠鏡緊才能升空飛行。

FORBIDDEN

# LOCATE AN APPROPRIATE LOCATION 遠離障礙物及人群

R/C helicopters fly at high speed, thus posing a certain degree of potential danger. Choose a legal flying field consisting of flat, smooth ground without obstacles. Do not fly near buildings, high voltage cables, or trees to ensure the safety of yourself, others and your model. For the first practice, please choose a legal flying field. Do not fly your model in inclement weather, such as rain, wind, snow or darkness.

直昇機飛行時具有一定的速度,相對的也潛在著危險性,塌地的選擇也相對的重要,請需遵守當地法規到合法遙控飛行場 地飛行・務め選擇在空礦合法專廳飛行場地,並必須注意周遭有沒有人、高樓、建築物、高壓電線、樹木等等,避免操將 的不當造成自己與他人財產的損壞。請勿在下雨、打雷等惡劣天候下操作,以確保本身及機體的安全。



FORBIDDEN

# NOTE ON LITHIUM POLYMER BATTERIES 鋰聚電池注意事項

Lithium Polymer batteries are significantly more volatile than alkaline or Ni-Cd/Ni-MH batteries used in RC applications. All manufacturer's instructions and warnings must be followed closely. Mishandling of Li-Po batteries can result in fire. Always follow the manufacturer's instructions when disposing of Lithium Polymer batteries.

鋰聚電池跟一般在RC使用的鹼性電池、鎳鎬電池、鍊氫電池比較起來是相對危險的。請嚴格遵守鋰聚電池說明書之使用注意事項。不恰當使用鋰聚電池,可能造成火災並備及生命財產安全,切勿大意!



○ FORBIDDEN 禁止

## PREVENT MOISTURE 遠離潮濕環境

R/C models are composed of many precision electrical components. It is critical to keep the model and associated equipment away from moisture and other contaminants. The introduction or exposure to water or moisture in any form can cause the model to malfunction resulting in loss of use, or a crash. Do not operate or expose to rain or moisture.

直昇機內部也是由許多精密的電子零組件組成,所以必須絕對的防止潮濕或水氣,避免在浴室或雨天時使用,防止水氣進 入機身內部而導致機件及電子零件故障而引發不可預期的意外!



FORBIDDEN

## PROPER OPERATION 勿不當使用本產品

Please use the replacement of parts on the manual to ensure the safety of instructors. This product is for R/C model, so do not use for other purpose.

請勿自行改造加工,任何的升級改裝或維修,請使用亞拓產品目錄中的零件,以確保結構的安全。 請確認於產品限界內操作,請勿過載使用,並勿用於安全、法令外其它非法用途。



WARNING

## **OBTAIN THE ASSISTANCE OF AN EXPERIENCED PILOT** 避免獨自操控

Before turning on your model and transmitter, check to make sure no one else is operating on the same frequency. Frequency interference can cause your model, or other models to crash. The guidance provided by an experienced pilot will be invaluable for the assembly, tuning, trimming, and actual first flight or unforeseen danger may happen. (Recommend you to practice with computer-based flight simulator.)

至飛行場飛行前,需確認是否有相同頻率的同好正進行飛行,因為關格相同頻率的發射器將導致自己與他人立即干擾等意外危險。遙控飛機操控技巧在學習初期有著一定的難度,要盡量避免獨自操作飛行,需有經驗的人士在旁指導,才可以操控飛行,否則將可能造成不可預期的意外發生。(勤練電腦模擬器及老手指導是入門必要的選擇)



WARNING

# SAFE OPERATION 安全操作

Make sure to always be aware to keep your eyes and body away from blades rotation. Do not attempt to grab or make contact with the helicopter while the main blades are in motion. During take-off, landing, and flight, be sure to keep the helicopter away from all obstacles. Operators must stand at least 10 meters away from the helicopter. Never take your eyes off the model or leave it unattended while it is turned on, and Immediately turn off the model and transmitter when you have landed the model. Operate this unit within your ability, do not fly under tired condition, Improper operation may cause in danger, and always to avoid injury caused by loose parts due to improper assembly or any unforeseen dangers.

請隨時注意,無論在任何時候,都不能將運轉中的旋翼對著眼睛,嚴禁用手抓取運行中的直昇機,當主旋翼轉動後,或 起飛/試飛時,務必遠離障礙物,站立位置必需距離5公尺以上,不可在視線範圍外進行飛行,降落後也猜馬上關掉直 昇機和遙控器電源。操作這台直昇機需要一定操控技術及能力,避免因人為組裝不當造成零件說落,而引發不可預期的 財物及人員損傷,並請衡量自身情況,過於疲勞、精神不佳或不當操作,都可能引請不可預期的意外發生。





**企業意** 

# ALWAYS BE AWARE OF THE ROTATING BLADES 遠離運轉中零件

During the operation of the helicopter, the main rotor and tail rotor will be spinning at a high rate of speed. The blades are capable of inflicting serious bodily injury and damage to the environment. Be conscious of your actions, and careful to keep your face, eyes, hands, and loose clothing away from the blades. Always fly the model a safe distance from yourself and others, as well as surrounding objects.

直昇機主旋翼與尾旋翼運轉時會以高轉速下進行,在高轉速下的旋翼會造成自己與他人在身體上或環境上的嚴重損傷, 請勿觸摸運轉中的主旋翼與尾旋翼,並保持安全距離以避免造成危險及損壞。



**企AUTION** 注意

### KEEP AWAY FROM HEAT 遠離熱源

R/C models are made of various forms of plastic. Plastic is very susceptible to damage or deformation due to extreme heat and cold climate. Make sure not to store the model near any source of heat such as an oven, or heater. It is best to store the model indoors, in a climate-controlled, room temperature environment.

述控积機多半是以 PA 續維或聚乙烯、電子商品為主要材質,因此要盡量遠離熱源、日聽,以避免因高溫而變形甚至熔毀 損壞的可能。



# RADIO TRANSMITTER AND ELECTRONIC EQUIPMENT REQUIRED FOR ASSEMBLY

自備遙控及電子設備





Transmitter (7-channel or more,helicopter system) 發射器(七動以上直昇機模式遊控器)



Intelligent Balance Charger RCC-6CX 智慧型分配充電器 RCC-6CX



**RCC-300 Battery Charger** RCC-300 充電器





Receiver(7-channel or more) 接收器(七勤以上)

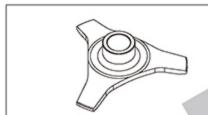


Remote Receiver



22.2V 6S 4500~5200mAh Li-Po Battery x 2 pcs 22.2V 6S 4500~5200mAh Li-Po 電池 x 2

## ADDITIONAL TOOLS REQUIRED FOR ASSEMBLY 自備工具



Swashplate Leveler 十字盤調整器



Philips Screw Driver 十字螺絲起子 φ 3.0/ φ 1.8mm



Cutter Knife 刀子



Digital Pitch Gauge 電子螺距規



Hexagon Screw Driver 六角螺絲起子 3mm/2.5mm/2mm/1.5mm



**Needle Nose Pliers** 



Multi-function Tester Voltmeter/Servo Diagnosis 多功能檢測計 電池電壓/伺服器檢測



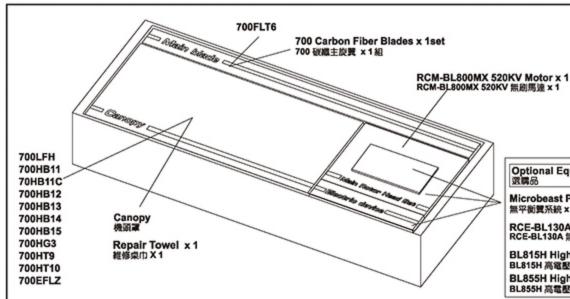
Oil



CA 影問鍵

# 4.PACKAGE ILLUSTRATION 包裝說明

ALIGN



Part Quick Finder



Optional Equipment 選購品

Microbeast PLUS Flybarless System x 1 無平衡質系統 x 1

RCE-BL130A Brushless ESC x 1 RCE-BL130A 無別調速器 x 1

BL815H High Voltage Brushless Servo x 3 BL815H 高電壓無別伺服器 x 3 BL855H High Voltage Brushless Servo x 1

BL855H 高電壓無別伺服器 x 1

There are many versions of T-REX 700L V2 for your choice. The Super Combo includes additional electronics and other equipment. The Instruction Manual will reference the T-REX 700L V2 Super Combo. You may purchase any additional items referenced in the instruction manual or any spare parts for other 700L V2 version by referring to more product information in this manual.

T-REX 700L V2 系列商品有多種版本可作為選擇,除標準配備 會因您購買的商品版本而有些微不同,在組裝、設定上都是 -致的,在此我們以 Super Combo作為操作範例,您也可依 照書面上的商品資訊來增添其他選購商品。



## [RH70E30XT] T-REX 700L V2 SUPER COMBO STANDARD EQUIPMENT T-REX 700L V2 SUPER COMBO 標準配備 700HC8 700FLH 700HB11 700HB11C 700HB12 700HB13 700HT9 700LFLZ 700HB14 700HB15 700HG3 700HT10



700FLT6

700 Carbon Fiber Blades x 1set 700 碳纖主旋翼 x 1組



Repair Towel x 1 維修桌巾 X 1



RCE-BL130A Brushless ESC RCE-BL130A無刷調速器



Microbeast PLUS Flybarless System x 1 無平衡翼系統×1



BL815H High Voltage Brushless Servi BL815H 高電壓無副伺服器 x3



ss Servo x 3 BL855H High Voltage Brushless Servo x 1 器 x3 BL855H 高電壓無別伺服器 x1



M4x4 止洩螺絲 x 2 Motor Slant Thread Pinion Gear 12T x 1 馬達斜齒輪 12T x 1



RCM-BL800MX 520KV Brushless Motor x 1 RCM-BL800MX 520KV無限馬達×1

## T-REX 700L V2 KIT STANDARD EQUIPMENT T-REX 700L V2 KIT標準配備





700HC8



700FLH



700HB11



700HB11C



700HB12



700HB13



700HB14



700HB15



700HG3



700HT9



700HT10



700LFLZ



700FLT6



700 Carbon Fiber Blades x 1set 700 砂罐主炒菜×1組



Repair Towel x 1 維修桌巾 X 1



M4x4 Set Screw x 2 M4x4 止洩螺絲 x 2 Motor Slant Thread Pinion Gear 12T x 1



RCM-BL800MX 520KV Brushless Motor x 1 RCM-BL800MX 520KV無限馬達 x 1

#### CAREFULLY INSPECT BEFORE REAL FLIGHT 請嚴格執行飛行前之檢查義務

- Before flying, please check to make sure no one else is operating on the same frequency for the safety.
- · Before flight, please check if the batteries of transmitter and receiver are enough for the flight.
- · Before turn on the transmitter, please check if the throttle stick is in the lowest position. IDLE switch is OFF.
- · When turn off the unit, please follow the power on/off procedure. Power ON- Please turn on the transmitter first, and then turn on receiver. Power OFF- Please turn off the receiver first and then turn off the transmitter. Improper procedure may cause out of control, so please to have this correct habit.
- · Before operation, check every movement is smooth and directions are correct. Carefully inspect servos for interference and broken gear.
- · Check for missing or loose screws and nuts. See if there is any cracked and incomplete assembly of parts. Carefully check main rotor blades and rotor holders. Broken and premature failures of parts possibly cause resulting in a dangerous situation.
- Check all ball links to avoid excess play and replace as needed. Failure to do so will result in poor flight stability.
- · Check if the battery and power plug are fastened. Vibration and violent flight may cause the plug loose and result out of control.
- · 每次飛行前應先確認所使用的頻率是否會干擾他人,以確保您自身與他人的安全。
- 每次飛行前確定您發射器與接收器電池的電量是在足夠飛行的狀態。
- · 開機前確認油門搖桿是否位於最低點,熄火降落開關,定速開闢(IDLE)是否於關閉位置。
- 關機時必須遵守電源開關機的程序,開機時應先開啟發射器後,再開啟接收器電源;關機時應先關閉接收器後,再關閉發射器電源。不正確的開關程序可能會 造失控的現象,影響自身與他人的安全,請養成正確的習慣。
- 門機請先確定直昇機的各個動作是否順暢,及方向是否正確,並檢查伺服器的動作是否有干涉或崩縮的情形,使用故障的伺服器將導致不可預期的危險。
- 飛行前確認沒有缺少或鬆脫的螺絲與螺帽,確認沒有組裝不完整或損毀的零件,仔細檢查主旋翼是否有損壞,特別是接近主旋翼夾座的部位。損壞或組裝不完 整的零件不僅影離飛行 ,更會造成不可預期的危險。注意:每次飛行前的安全檢查、保養、及更換損耗零件,請確實嚴格執行以確 保安全。
- 檢查所有的連桿頭是否有鬆脫的情形,過鬆的連桿頭應先更新,否則將造成直昇機無法操控的危險。
- 確認電池及電源接頭是否固定牢靠,飛行中的震動或激烈的飛行,可能造成電源接頭鬆號而造成失控的危險。

When you see the marks as below, please use glue or grease to ensure flying safety.

標有以下符號之組裝步驟,請配合上膠或上油,以確保使用之可靠度。

CA: Apply CA Glue to fix.
AB: Apply AB Glue to fix.
R48: Apply Anaerobics Retainer to fix.
T43: Apply Thread Lock to fix.
OIL: Add Grease.

CA:使用瞬間膠固定 AB:使用AB膠固定

R48 :使用金屬管狀固定缺氧膠固定

T43:使用螺絲器

OIL:添加潤滑油

When assembling ball links, make sure the "A" character faces outside.

各項塑膠製連桿頭扣接時·A字請朝外·



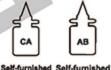
洒滑油

Green

線色



藍色





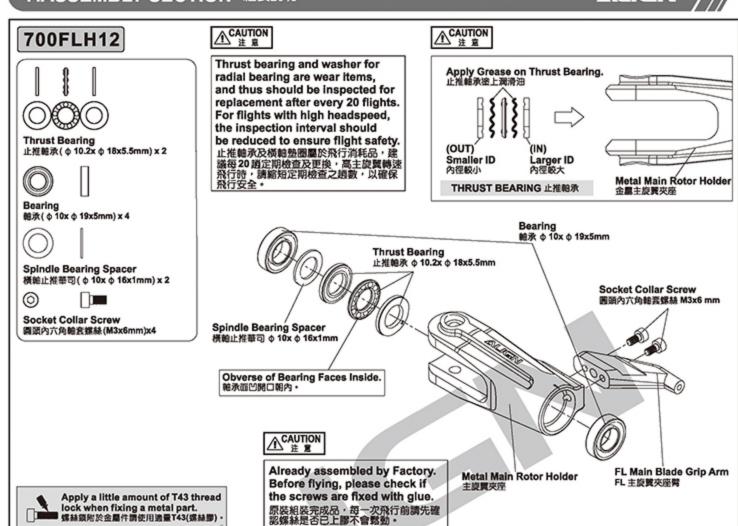
T43 Glue width : approx. 1mm T43上膠寬度約1mm

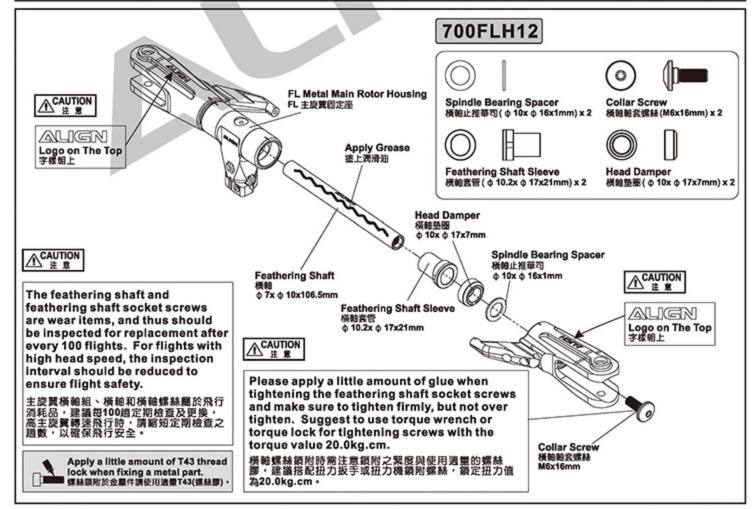
R48 metal tubular adhesive (eg. Bearings). T43 thread lock, apply a small amount on screws or metal parts and wipe surplus off. When disassembling, recommend to heat the metal joint about 15 Seconds. (NOTE: Keep plastic parts away from heat.)

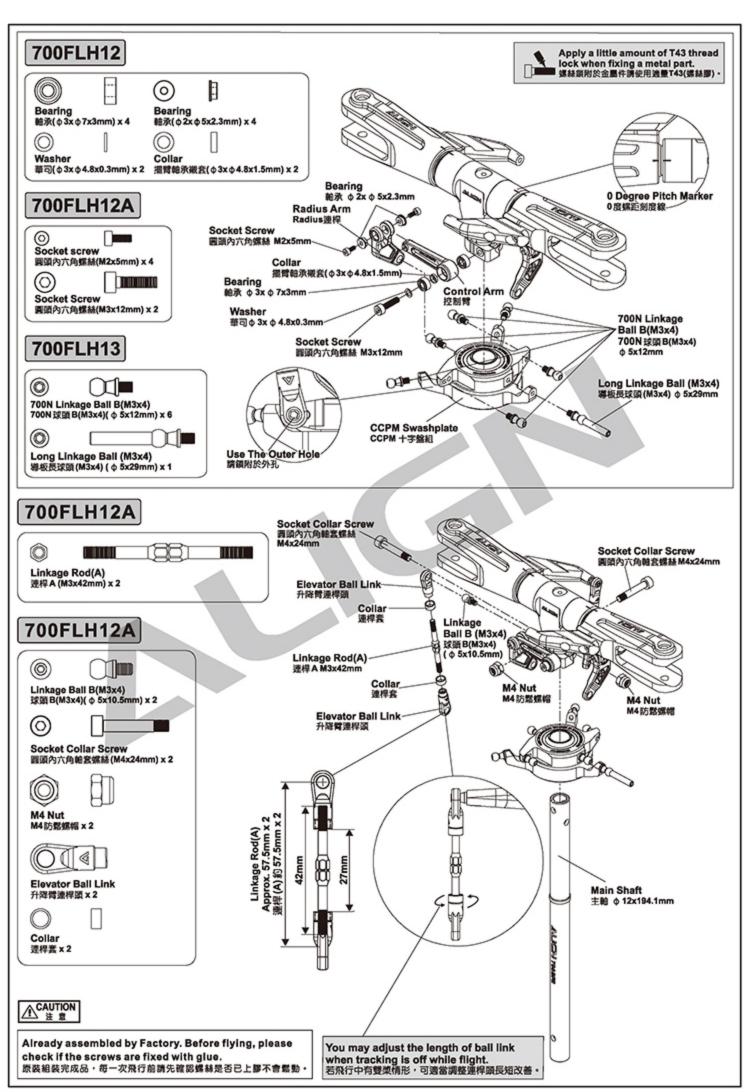
瞬臂膠(自備) AB膠(自備)

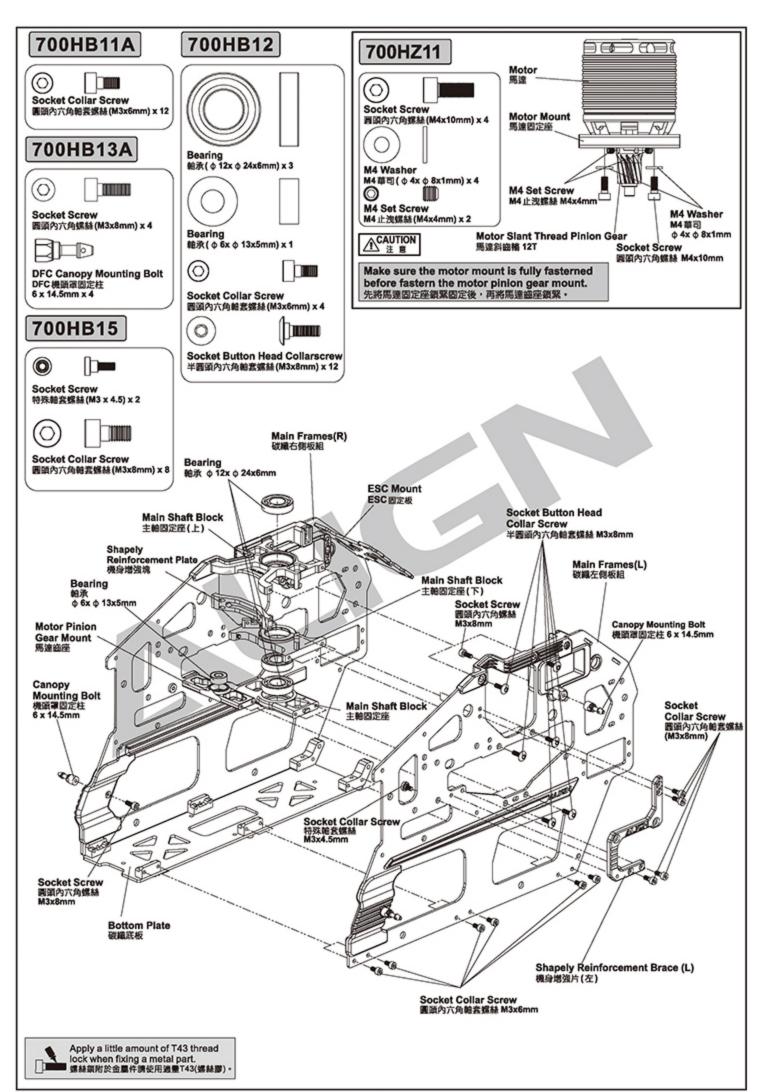
R48 為強力金屬管狀 (如軸承)接著劑,T43 為螺絲膠,膠合螺絲或金屬內外徑購務必 少量使用,必要時請用手去除多餘腳量,欲拆卸時可於金屬接合部位熱烤約15秒。

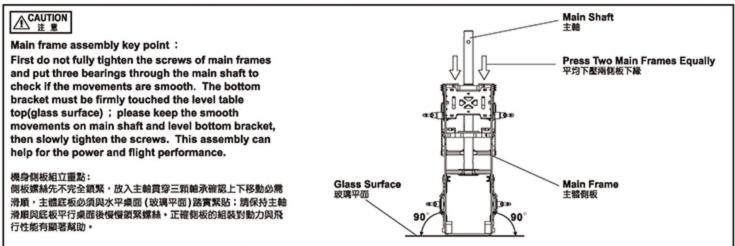
(注意! 塑膠件避免接近熱源)

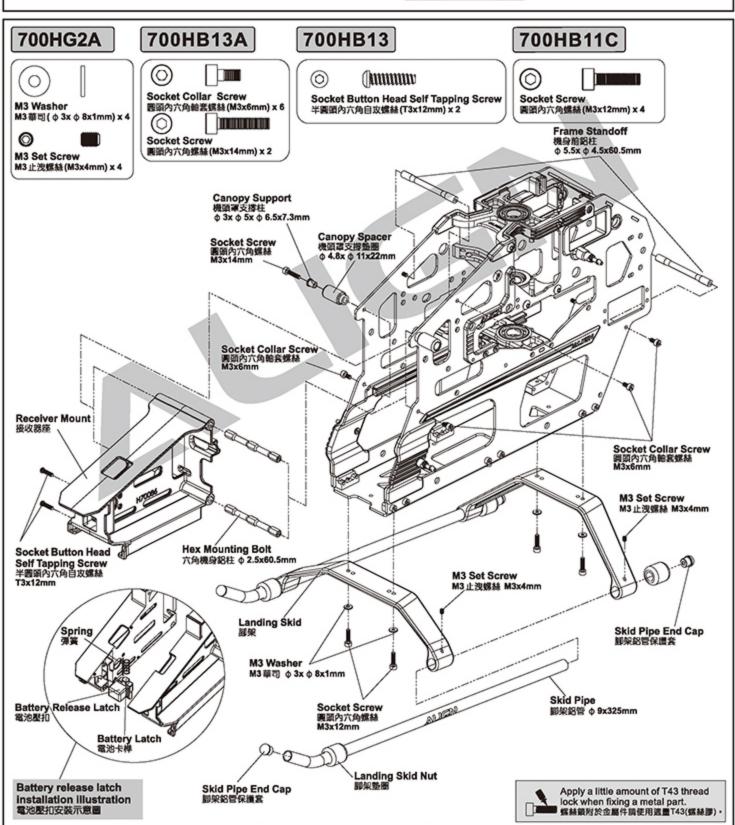


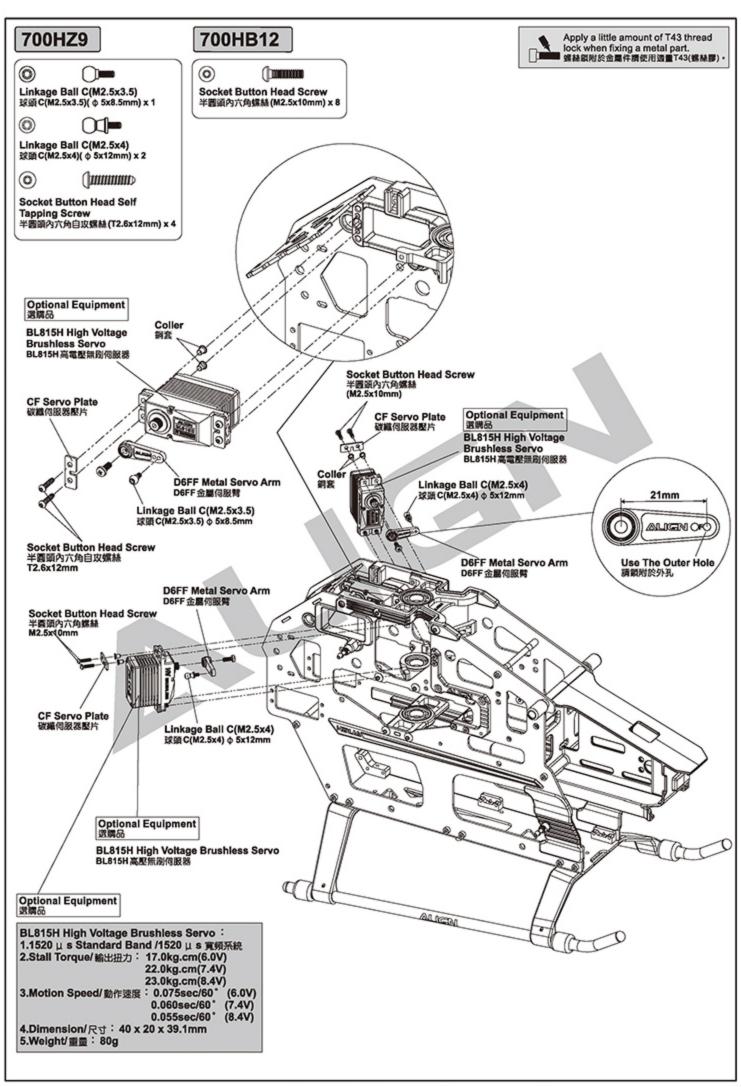


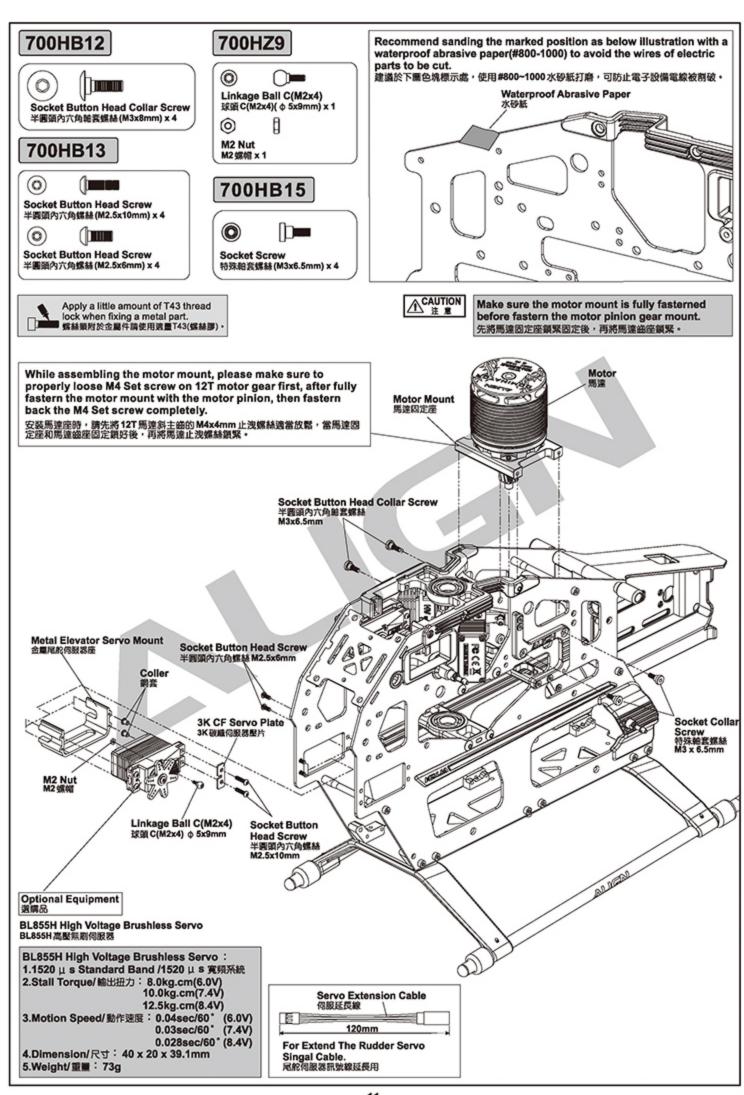


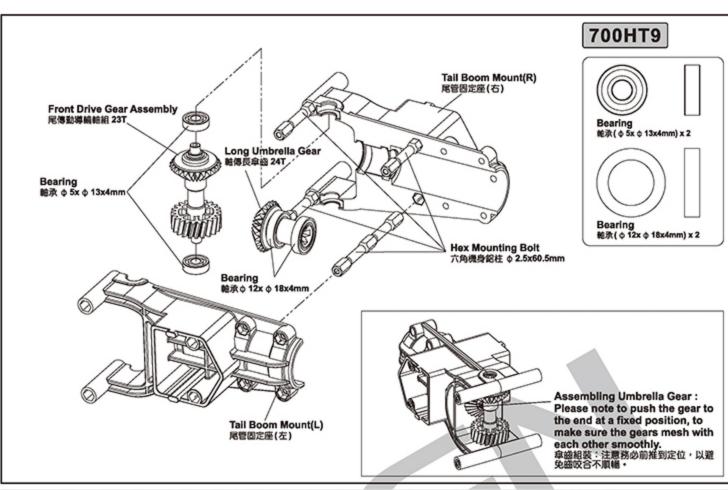


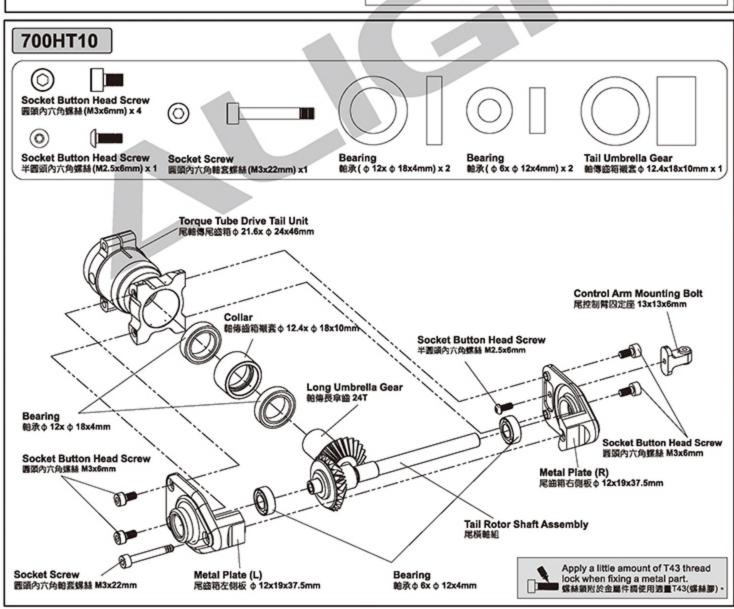


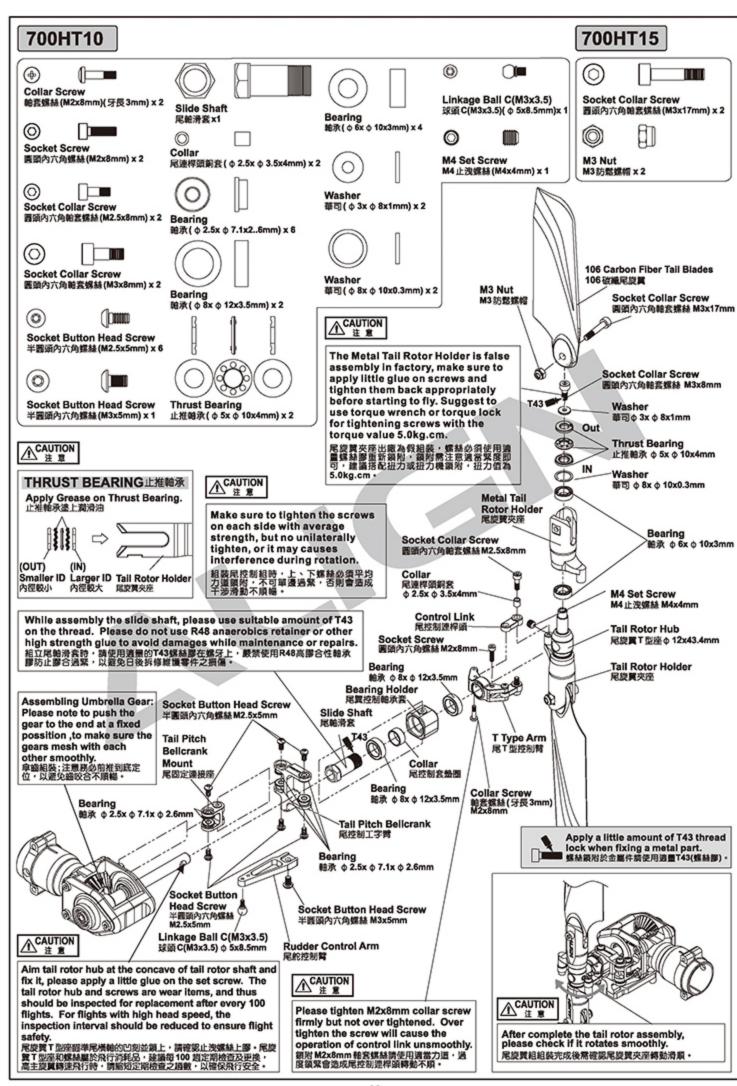


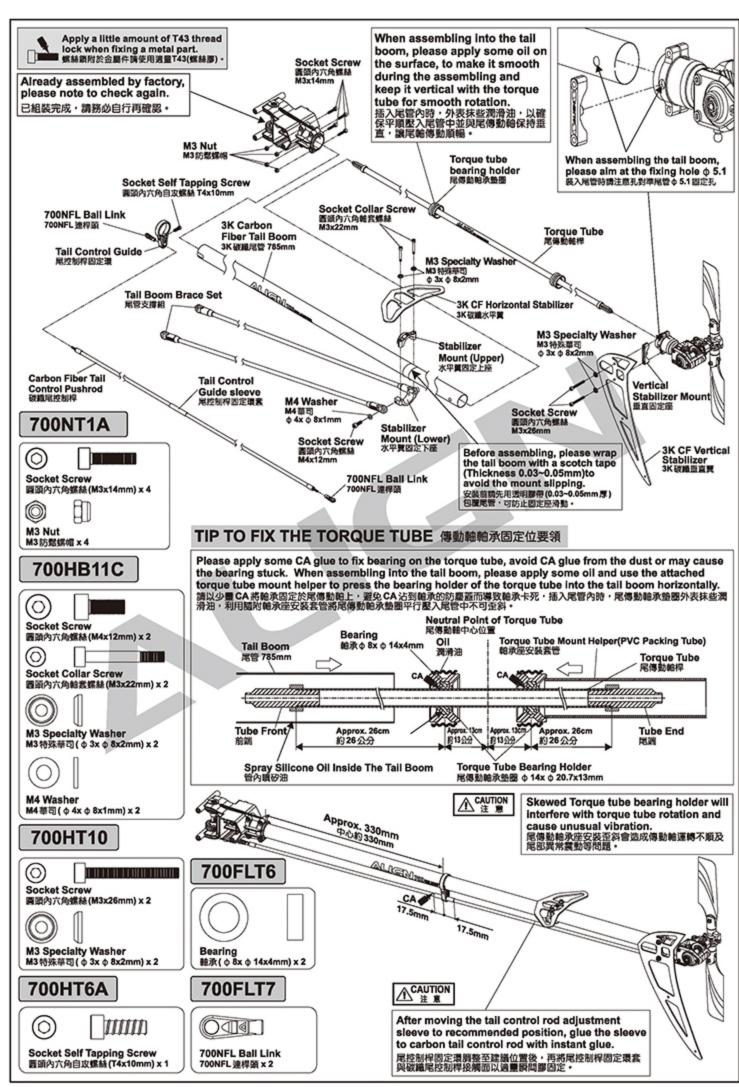


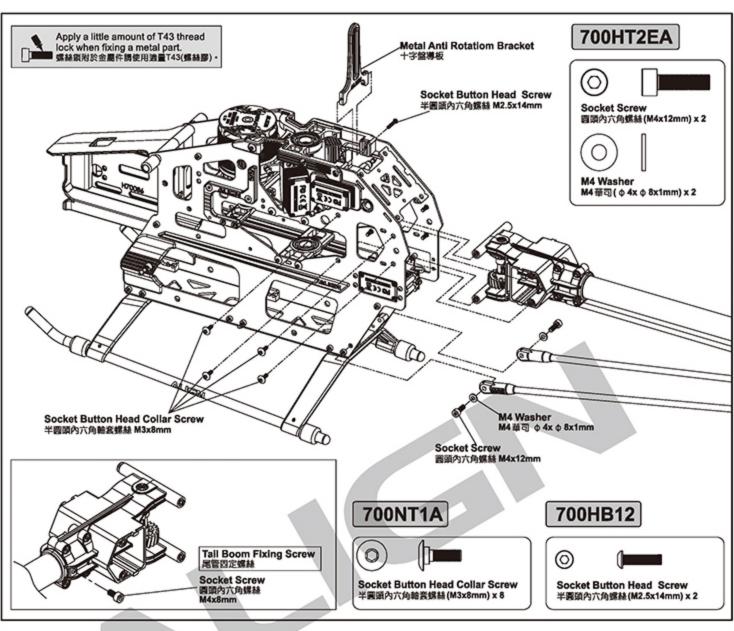


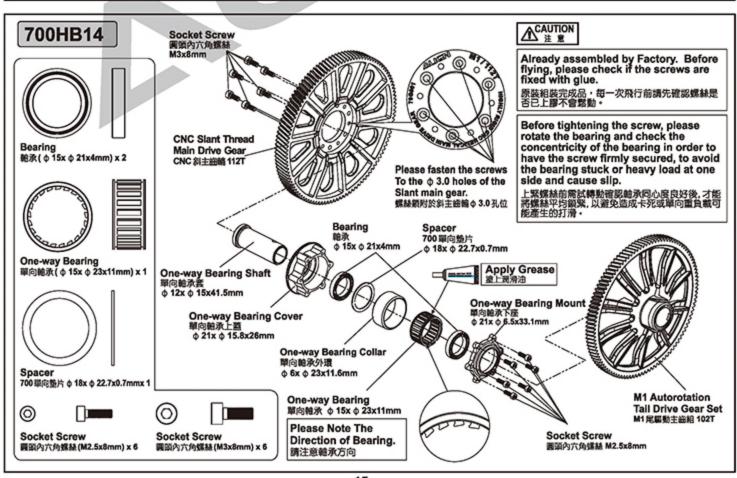


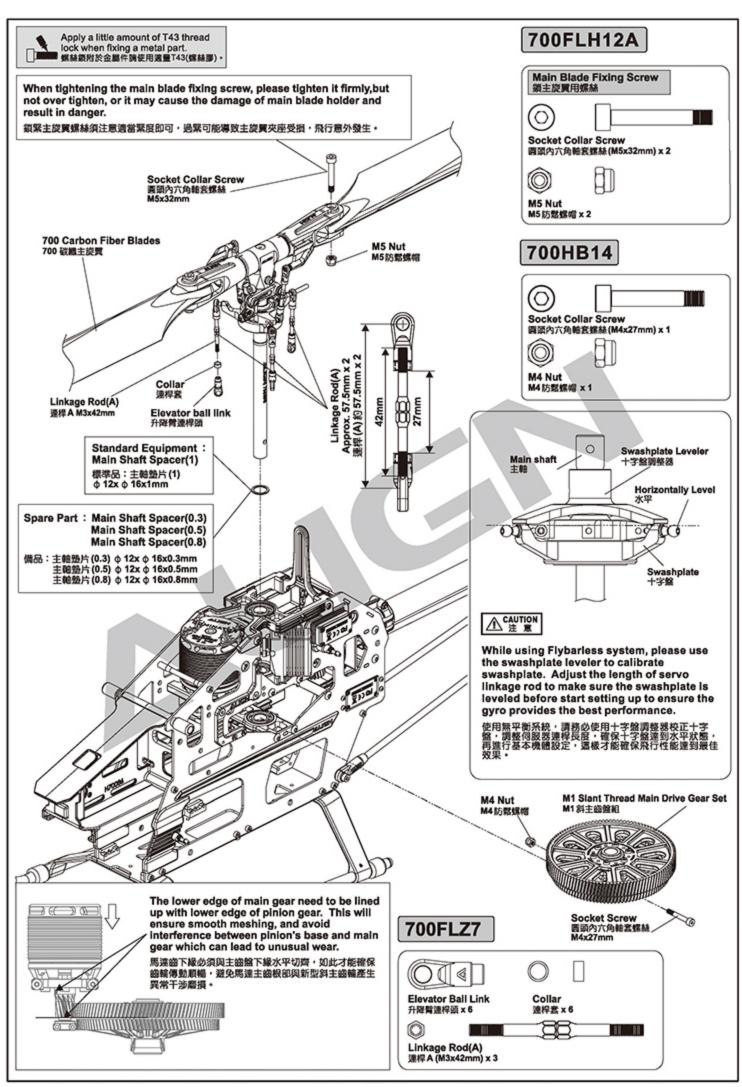


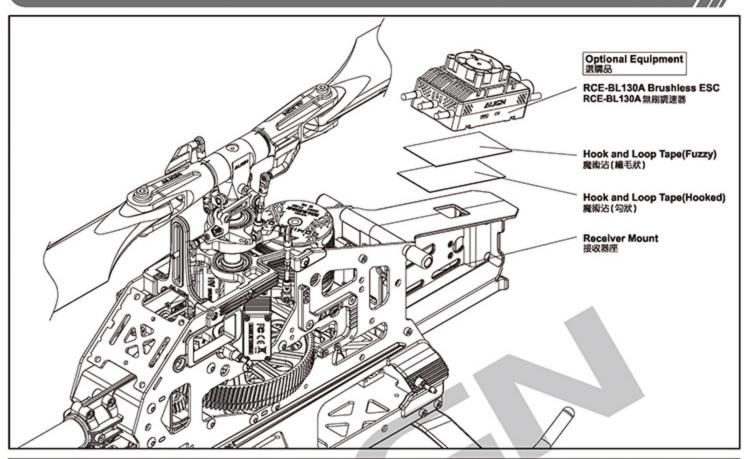


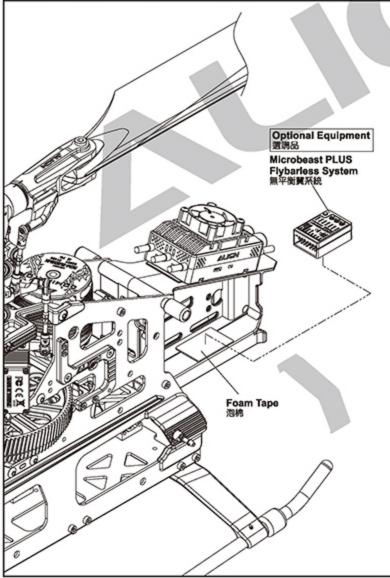












# A MOUNTING ORIENTATION OF MICROBEAST PLUS MICROBEAST PLUS的安裝方向

The Microbeast PLUS unit can be mounted in nearly all possible orientations. The only restriction is that the plug connectors have to point in or against flying direction and the egdes of the unit must be parallel to the rotation axis.

You have to choose whether MICROBEAST PLUS is mounted horizontally (printed surface 90 degrees to the main shaft) or vertically (printed surface in parallel with the main shaft).

MICROBEAST PLUS可以安裝在機體的任何位置。唯一的限制是接線口必須和飛行方向一致。

您可以選擇水平安裝(印刷面與主軸呈垂直90度)、或垂直安裝 (印刷面與主軸呈平行)。

# THE COLOR OF THE STATUS-LED SHOWS THE CURRENTLY SELECTED ORIENTATION:

LED指示燈狀態顯示安裝方向:

Status-LED	Mounting Orientation
Status-LED燈	安裝方向
Blue	Horizontal (Flat)*
藍色	水平(平)*
Red	Vertical(on The Side)
紅色	垂直(侧面)

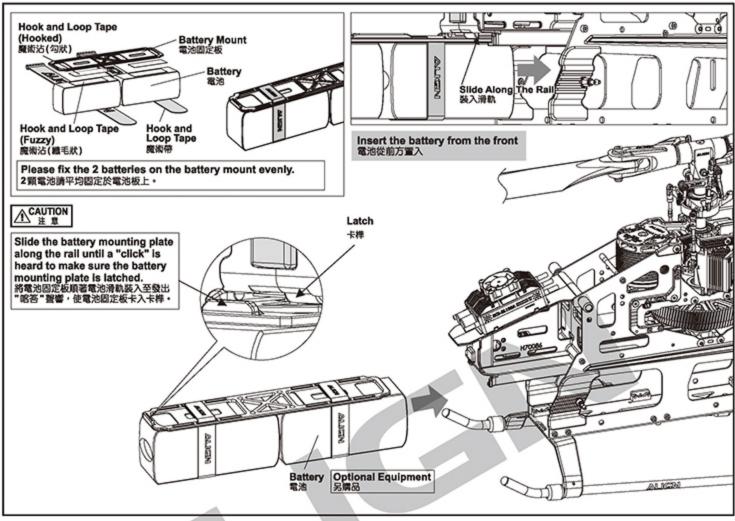
\*Factory Setting \*出廠預設值

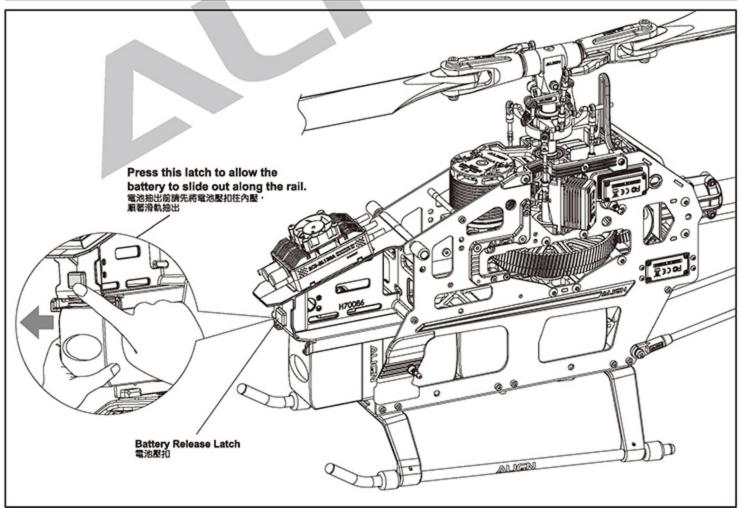


Status-LED: Blue Status-LED撒:藍色

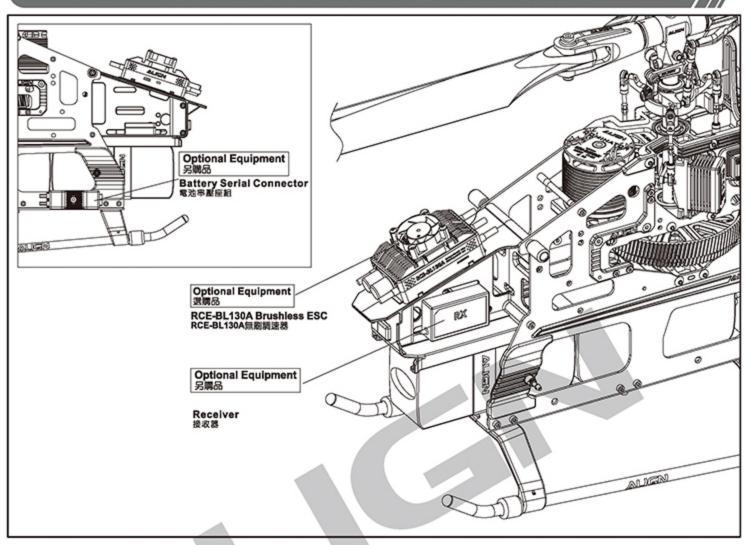


Status-LED: Red Status-LED燈: 紅色



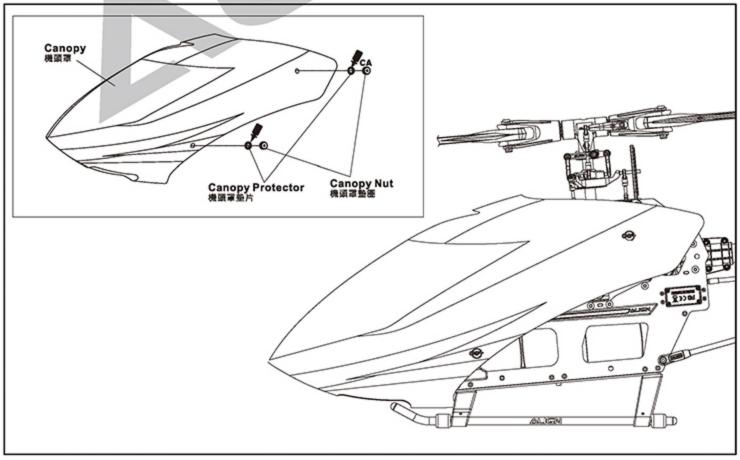


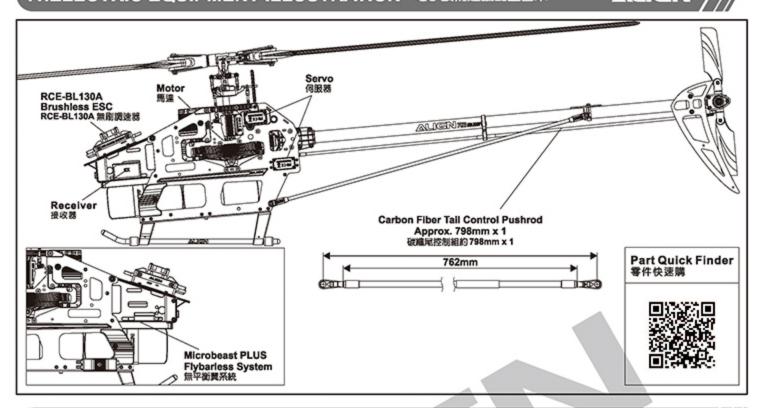
# 9.INSTALLATION FOR ESC AND RECEIVER 無刷調速器與接收器安裝 ALIGN



# 10.CANOPY ASSEMBLY 機頭罩安裝

ALIGN





# 12.MICROBEAST PLUS FLYBARLESS MANUAL 無平衡翼系統使用說明

ALIGN

MICROBEAST PLUS Flybarless System as ALIGN helicopter standard equipment, must and compatible with ALIGN standard equipment including blades, servos, motor, battery and so on, please refer to flight and setup instruction in this manual.

ALIGN helicopter標配使用MICROBEAST PLUS無平衡質系統,須搭配ALIGN直昇機標準配件(主旋翼、伺服器、馬達)與飛行操作、設定指示。

## USER NOTICE 使用注意事項



- 1.If assembling and operating the helicopter without using ALIGN standard equipment, including electronic equipment & blades...etc, please make sure there is a sufficiently large and stable power supply to your helicopter. If any abnormal voltage or insufficient power supply, suggest to upgrade the flybarless system to MICROBEAST PLUS HD (Optional) for better power back up.
- 2. Please refer to BEASTX MICROBEAST PLUS/HD website for MICROBEAST PLUS/HD assembly and setup instruction.
- 3.Any over use, incorrect setup, assembly, modification or misuse will lead to abnormal voltage, electronic devices damage, structural interference, and insufficient power supply. Make sure to carefully check every assembly and setup refer to the manual instruction prior to every flight to prevent any unforeseen danger.
- 1.安装、操控您的直昇機時,如非使用ALIGN標準配件(含電子配件、主旋翼等),請務必確定您的供電系統有足夠的供電能力,如發現電壓異常、供電不足,建議您升級使用MICROBEAST PLUS HD無平衡翼系統(選配),以能確保充足、穩定的接收器電源。
- 2.MICROBEAST PLUS/HD使用、設定、接線・請參照 BEASTX MICROBEAST PLUS/HD官方說明。
- 3.任何電子配件、零件的設定、組裝、修改或操作不良所造成的電壓異常、電子零件損壞,即可能造成供電不穩定等問題,每趨飛行前須注意仔細檢查,防止機件及電子零件故障而引發不可預期的意外。

# MANUAL LINK 設定操作連結

MICROBEAST PLUS Flybarless System is the V4.2 version out of the factory, please feel at ease using it. You can also link to BEASTX MICROBEAST PLUS/HD website to get the latest version and the latest news. And please refer to MICROBEAST PLUS V3.2.x and V4.2 instruction manual for operating and setting.

MICROBEAST PLUS無平衡實系統,出廠時主程式為V4.2版本。您也可以連結至BEASTX MICROBEAST PLUS/HD官網查詢,隨時更新最新版本及各項最新訊息。操作設定請同時參照V3.2.x版及V4.2版使用說明書。



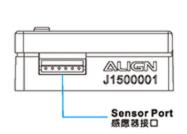
Please visit Align download area to get the completed instruction manual at Align website.

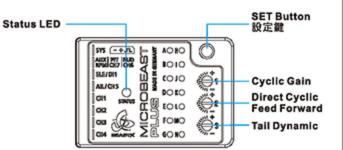
更多詳細的設定操作說明講至官網下載專區下載。 http://www.align.com.tw/beastx/



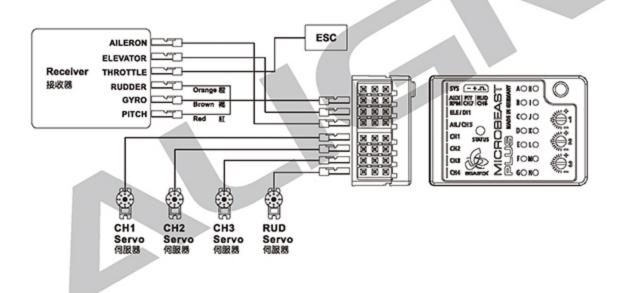
# PARTS IDENTIFICATION 各部位名稱

#### MICROBEAST PLUS FLYBARLESS SYSTEM 無平衡翼系統





#### MICROBEAST PLUS FLYBARLESS SYSTEM WIRING DIAGRAM 無平衡貿系統接示意圖





For detail connectivity, please scan QR Code then follow MICROBEAST PLUS manual.

詳細接線方式・臍搏描QR Code 連結至MICROBEAST PLUS放明書・

**企**CAUTION 注意



MICROBEAST PLUS HD Flybarless System(Optional) MICROBEAST PLUS HD無平衡翼系統(選配)

If assembling and operating the helicopter without using ALIGN standard equipment, including electronic equipment & blades...etc, please make sure there is a sufficiently large and stable power supply to your helicopter. If any abnormal voltage or insufficient power supply, suggest to upgrade the flybarless system to MICROBEAST PLUS HD (Optional) for better power back up. Please refer to BEASTX website for MICROBEAST PLUS HD assembly and setup instruction.

安裝、操控您的直昇機篩,如非使用 ALIGN 標準配件 (含電子配件、主旋實等),請務必確定您的供電系統有足夠的供電能力,如發現電壓異常、供電不足,建議您升級使用 MICROBEAST PLUS HD 無平衡翼系統 (選配),以能確保充足、穩定的接收器電源。MICROBEAST PLUS HD 使用、設定、接線,請參照 MICROBEAST PLUS HD 官方說明。

ALIGN

To set this option is to turn on the transmitter and connect to BEC power.

Note: For the safety, please do not connect ESC to the brushless motor before the setting in order to prevent any accident caused by the motor running during the setting.

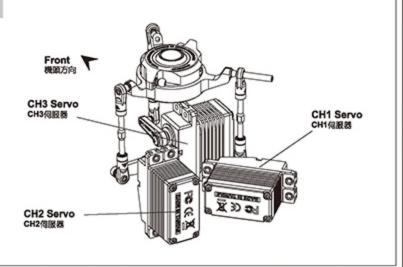
此項設定只要開啟發射器,接上BEC電源即可進行操作。

注意:為了安全起見,設定前請先不要將無別調速器與無別馬達三條線接上,以免調整時啟動馬達而發生危險。

## SERVO CONFIGURATION 伺服器配置

Following the servo configuration diagram on right, plug the servos to Gyro.

請依照右圍圖示的伺服器名稱·將伺服器接到陀螺儀。



# 14.ADJUSTMENTS FOR GYRO AND TAIL NEUTRAL SETTING 陀螺儀與尾翼中立點設定調整 🛕 LICEN

Turn off Revolution mixing(RVMX) mode on the transmitter, then set the gain switch on the transmitter and the gyro to non-Head lock mode, or disable gain completely. After setting the transmitter, connect the helicopter power and proceed with rudder neutral point setting. Note: When connecting to the helicopter power, please do not touch tail rudder stick and the helicopter, wait for 3 seconds for gyro to enable, and the rudder servo horn should be 90 degrees to the tail servo. Tail pitch slider should be halfway on the tail output shaft. This will be the standard rudder neutral point. After completing this setting, set the gain switch back to heading lock mode, with gain at around 70%.

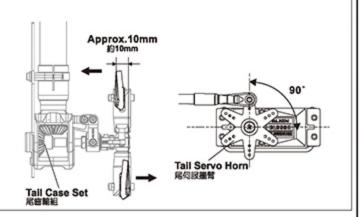
發射器內陀螺儀設定請關閉根軸混控模式,並將發射器上的感度開關與陀螺儀切至"非鎖定模式"或將陀螺儀感度關閉。發射器設定完成後接上直昇機電源,即可 進行尾舵中立點設置。注意:當接上直昇機電源時請勿接動尾舵搖桿或碰觸機體,待3秒陀螺儀開機完成後,尾伺服臂需與尾伺服器約成 90度,尾旋翼控制組須 正確置於尾橫輪約中間位置,即為標準尾舵中立點設定,設定完成後,切換至"鎖定模式",感度設約 70% 左右。

## TAIL NEUTRAL SETTING

#### 尾中立點設定

After the gyro is enable and under non-Head lock mode, correct setting position of tail servo and tail pitch assembly is as photo. If the tail pitch assembly is not in the middle position, please adjust the length of rudder control rod to trim.

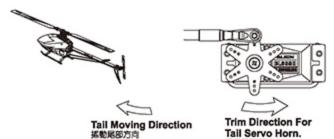
陀螺儀開機後,在非鎖定模式下,尾唇服器與尾 Pitch控制組正確擺置位置。若尾 Pitch控制組未置中時請調整尾控制連桿的長度來修正。



# HEAD LOCK DIRECTION SETTING OF GYRO 陀螺機鎖定方向設定

To check the head lock direction of gyro is to move the tail clockwise and the tail servo horn will be trimmed counterclockwise. If it trims in the reverse direction, please switch the gyro to "REVERSE".

陀螺儀鎮定方向確認,當手搖尾部順時鐘擺動,尾伺服臂應反時鐘修 正,反向時請切換陀螺儀上"鎖定反向"開關修正。

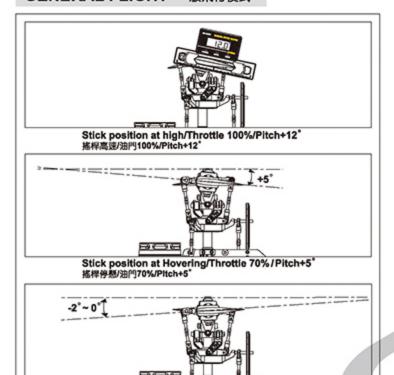


尾唇股臂修正方向

The rotational speed must set below 2,200RPM for safety to prevent any unexpected danger.

## 直昇機的主旋翼有安全使用轉速範圍,飛行時不可超過2,200 rpm,超轉會導致不可預期的危險,甚至危害他人生命財產。

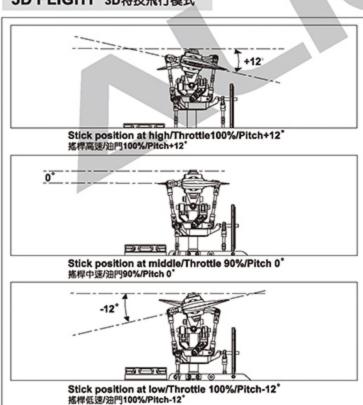
# GENERAL FLIGHT 一般飛行模式



Stick position at low/Throttle 0%/Pitch-2°~0°

# 3D FLIGHT 3D特技飛行模式

据桿低速/油門0%/Pitch-2~0\*

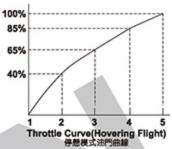


- (Aution 注 原 2. If the pitch is set too high, it will result in shorter flight duration and poor motor performance.

  3. Setting the throttle to provide a higher speed is preferable to increasing the pitch too high.
  - 1.螺距(Pitch)總行程約 ±15°。
  - 2.過大螺距設定,會導致動力與飛行時間降低。
  - 3.励力提昇以較高轉速的設定方式,優於螺距調大的設定。

# **GENERAL FLIGHT**

Throttle 油門		Pitch 螺距
5	100%High Speed 100%高速	+12*
4	85%	
3	60%~65%Hovering 60%~65%停懸	+5*
2	40%	
1	0% Low Speed 0%低速	-2° ~0°

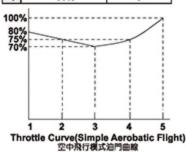


#### Pitch and Rotation Speed Pitch與轉速耗係

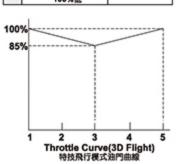
TIP:It is recommended to use a lower pitch This recommended to use a lower pitch setting when using higher RPM\Head speed. This will allow for better power. 搭配要源,如果使用較高轉速馬達動力建議搭配票低 Pitch,將獲得較佳動力效能。

#### IDLE 1:SPORT FLIGHT

	Throttle 油門	Pitch 螺距
5	100%	+10*~+12*
4	75%	
3	70%	+5"
2	75%	
1	80%	-5'



IDLE 2:3D FLIGHT			
Throttle Pitch 油門 螺距			
5	100% High 100%高	+12°	
3	85% Middle 85%⊕	0*	
1	100% Low	-12°	

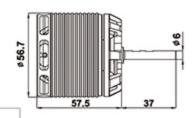




#### RCM-BL800MX (520KV/4530) MOTOR RCM-BL800MX (520KV/4530) 無刷馬達

Power and torque requirements of enthusiasts, the high output 800MX motor was born in Align's R&D lab. With dramatic increase in torque and power output, capable of 5100 watts continuous power output and 11000 watts of burst power! 800MX Motor has passed various thorough inspections made by our technical department, including motive testing, static testing, magnetic field testing, heat resistance and magnetic loss testing, running balance and vibration testing, noise testing, and many hours of actual loading and flying testing, etc. Align is proud to provide the latest innovations in RC Modeling to its consumers. Please enjoy your Align products safely.

亞拓特別針對玩家大動力、高扭力的需求,研發設計出為極致動力而生的800MX馬達,動力輸出與扭力表現大幅提升,持續輸出功率達5100W,瞬間最大輸出功率可達11000W。本公司生產的高扭力高轉速 800MX馬達,適用於RC 電動商品,其高功率高效率輸出特性,適合電動飛機/電動直昇機之高扭力高轉速驅動動力用途,速度控制可採本公司或市售規格無刷電子變速器。轉子採用高磁性材料效鐵磁精製而成,定子採用本廠 NC 自動繞線與高強度樹脂成型保護,耐高溫低震動。心軸採高硬度高鋼性軸承鋼及雙 ZZ 高速精密軸承設計,且經由亞拓獨立開發設計技術,使用壽命長、效率高、耐撞不易變形、低磁損、高效能800 型無刷馬達。該項新商品已通過本廠技術單位,實施精密嚴格動、靜態,磁場特性、強磁耐高溫磁損、連轉平衡震動及業音、負載實測飛行動態性能等全項嚴格檢測。





(Unit單位:mm)

SPECIFICATION	尺寸規格
---------------	------

KV	KV值	520KV(RPM/V)	Input Voltage	輸入電壓	DC 11.1~50.4V
Stator Diameter	定子外徑	45 mm	Stator Thickness	定子高度	30mm
Stator Arms	砂鋼片槽數	12	Magnet Poles	磁鐵極數	10
Max Continuous Current	最大持續電流	115A	Max Instantaneous Current	最大瞬間電流	250A(2sec/2秒)
Max Continuous Power	最大持續功率	5100W	Max Instantaneous Power	最大原題功率	11000W(2sec/2秒)
Dimension	尺寸	Shaft № Ø6x56.7x94.5mm	Weight	重量	Approx.約 508g

# 17.RCE-BL130A BRUSHLESS SPEED CONTROLLER INSTRUCTION MANUAL 無刷調速器使用説明 🛕 👢 🕻 🥌 N

# PRODUCT FEATURES 產品特色



RCE-BL130A Brushless ESC can be set up by ALIGN ASBOX Multifunction Programmer. So please scan QR code for ALIGN website start downloading for more information: http://www.align.com.tw/download-en/asbox/

RCE-BL130A無別調速器可透過ALIGN ASBOX 多功能設定盒進入參數設定,請掃描QR Code 連結亞拓網站下載相關資訊; http://www.align.com.tw/download-en/asbox/

- High performance microprocessor for excellent motor speed-governing and super soft start-up.
- · Microprocessor powered by independent DC regulator has better antiinterference performance, which greatly reduces the risk of losing control.
- · DEO (Driving Efficiency Optimization) Technology adopted greatly improves throttle response & driving efficiency, reduces ESC temperature.
- New switch-mode BEC with adjustable output voltage ranges from 5V to 8V and continuous/peak current of 10A/25A.
- BEC is separated from other circuits of the ESC, it may keep normal output even when MOSFET board of the ESC is burnt or breakdown.
- Multiple flight modes: Fixed-wing, Helicopter (Linear Throttle), Helicopter (Elf Governor), Helicopter (Store Governor).
- New governor program with adjustable governor parameter P/I brings excellent speed-governing function, keep the propeller revs stability when the load changes dramatically.
- Data logging records the standardized RPM, minimum voltage and maximum temperature of the flight.
- "Auto restart function" can manually interrupt the auto rotation and quickly restart the motor to avoid crashes caused by incorrect operations.
- · Independent output port for RPM (that is: motor speed) signals. · Separate programming port for ESC parameter setup through ALIGN ASBOX Multifunction Programmer.
- WIFI module for programming the ESC wirelessly with your smart phone (IOS or Android).
- · Allow for data checking, ESC programming, speed curve checking, and firmware upgrade online. (ALIGN ASBOX Multifunction Programmer or WIFI Express is needed)

- 相容多種無別馬達,具備優異
- 微處理器採用獨立的穩壓IC給供電,具有更好的抗干 操能力,降低失控的可能性。
- 採用同步整流驅動效率優化技術(DEO, Driving Efficiency Optimization) 油門回應更快,驅動效率 更高,電子調速器溫度更低。
- 使用新的大功率開關穩壓BEC,輸出電壓在5-8V之間 可護,瞬間輸出電流提升至25A。
- ·BEC模組和電子調速器其他電路相互獨立,當電子調 速器功率板出現燒毀等故障時,最大限度保證BEC正 常輸出,提供救機機會;
- 具有 "固定翼模式/直升機線性油門模式/直升機定速模式/直升機存储定速模式" 4種飛行模式。
- 使用新的直升機定速程式,定速感度可調,易於操作:具有優異的定速效果,在負荷急創變化的情况下,保證螺旋獎轉逐穩定。
- 具有飛行資料記錄功能,可記錄當次飛行的最低電 壓、最高溫度資料、最大電流、標定轉速。
- 具有熄火降落保護功能,在保護時間內可手動中斷熄 火降落過程並快速重新啟動馬達,避免因失控而墜 機。
- · 具有轉速 (RPM) 訊號輸出介面 •
- 具備獨立參數設定介面,用於連接多功能LCD專業程 式設計ALIGN ASBOX 多功能設定盒進行參數設定。
- 支援WIFI無線設定,通過手機端(蘋果&安卓)軟體可完 成所有參數設置(需要WIFI模組)。
- 支援線上讚取、設定電設定數,查看速度曲線表(存 儲模式下),升級電子調速器固件(需要LCD参數設 定盒或WIFI模組)。

## SPECIFICATIONS 產品規格

Model	Main Applications	Input Voltage	Cont./Peak Current (10s)	BEC Voltage
型號	應用範圍	輸入電壓	持續/瞬間(10秒)電流	BEC
Helicopter (Propeller: (2 600-700mm) 6-		6~12S LiPo Battery (22.2V~44.4V) 6~12S鋰電池 (22.2V~44.4V)	130A/200A	Switch-mode, 5V~8V Adjustable Voltage (Step: 0.1V),10A/25A Cont./Peak Current 開聯穩壓BEC,輸出電壓5V~8V可謂(調整幅度為0.1V每階),輸出電流持續 10A,瞬間25A
RCE-BL130A	Throttle Signal/BEC Output Wire/RPM Signal Transmission Wire		Size/Weight	Separate Programming Port
Brushless ESC	油門信號/BEC輸出線/RPM信號傳輸線		尺寸/重量	獨立參數程式設計介面
	White: Throttle Signal Wire / Red/Black, Red/Brown: BEC Output Wire / Yellow: RPM Signal Transmission Wire 白色為油門信號線/紅黑和紅棕二色線為BEC輸出線/黃色 為RPM信號傳輸線		92x45.5x28.5mm/195g	For connecting ALIGN ASBOX Multifunction Programmer, WIFI module, or cooling fan. 用於連接多功能LCD專業程式設計設 定盒或WIFI模組,可為輔助散熱風 扇供電

# USER GUIDE 使用說明書

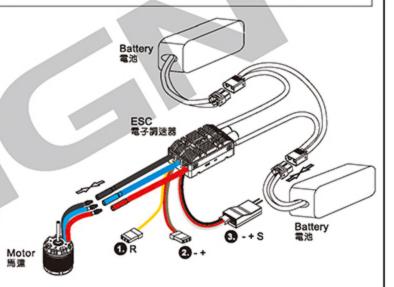
# **▲ CAUTION** 注意

The default throttle range of this ESC is from  $1100 \,\mu$ s to  $1940 \,\mu$ s, so you need to re-calibrate the throttle range when the first time you use this ESC or after you replace the transmitter.

電子調速器的油門行程出廠預設值為1100μs~1940μs,當首次使用電子調速器或者更換其他遙控器使用時,均應重新設定油門行程。

#### I.Connections 接線示意圖

- RPM Signal Wire(Yellow): plug it into the RPM input channel on the flybarless system. (This wire can be used for providing RPM signal data when using external speed-governing device.
- BEC Output Wire (Red/Brown): plug it into the battery channel or any unoccupied channel on the receiver. (For better BEC power supply, we recommend plugging this wire into the battery channel or any unoccupied channel on FBL system if the FBL system is permitted.
- Throttle Signal Wire (White/Red/Black): plug it into the throttle channel on the receiver or the corresponding channel on the FBL system, such as RX B channel on the VBAR system. For which channel you should plug it in, it depends on what kind of receiver and FBL system you use. The White wire is for transmitting throttle signals, the Red & Black cables are parallely connected in the BEC output wire, which means BEC voltage output wire and ground cable.



- RPM信號線(黃):插入無平衡翼系統轉速輸入通道;(當使用外部定速時,可使用RPM信號線提供轉速信號輸入。)
- ② BEC輸出線(紅、棕):這條額外的BEC輸出線插入接收機電池専用通道或任意空間通道。(為獲得更好的BEC供電效果,在無平衡實系統允許的情況下,建議將BEC線插入無平衡實系統的電池専用通道或任意空間通道。)
- ③ 油門信號線(白、紅、黑):插入接收機油門通道或無平衡翼系統對應通道,如VBAR系統的RXB通道,依接收機類型及無平衡翼系統類型而定。其中白線用於傳送油門信號,而紅線和黑線分別並聯在內部BEC的輸出端(即BEC電壓輸出線和地線)。

#### II.Throttle Range Calibration 油門行程校準操作方法

#### **企**CAUTION 注意

During the ESC/Radio calibration, please set the throttle curve to NORMAL and ensure the corresponding throttle amounts to the maximum throttle endpoint and the minimum throttle endpoint on your transmitter are respectively 100% and 0%.

進行油門行程校準時,請將油門曲線設置為NORMAL,並確保遙控器油門最高點對應的油門值為100%,油門最低點對應的油門值為0%

Turn on the transmitter and move the throttle stick to the top position. 開放監控器,將油門打到最高監

Connect the ESC to a battery. The motor will emit → 123" indicating the ESC is powered on normally. 索之调连接烧费验,属漆编印"123"提

は子調速器接電池・馬達鳴叫"123"提音・表示供電正常

5 seconds later, the motor will emit two short beeps indicating the maximum throttle position has been successfully calibrated and accepted.

等待5秒,馬達發出"嗶-嗶-"雙短鳴音,表示油門最高點校 準成功

Move the throttle stick to the bottom position. 1 second later, a short beep will emit indicating the minimum throttle position has been accepted.

將油門搖杆推到最低,等待1秒,油門最低點校準成功

The ESC will keep beeping indicating the number of LiPo cells you have plugged in.

馬達發出N聲鳴音,表示鋰電池Cell數

A long beep represents system is well done, ready to fly. 6.

馬達發出"噗"一聲長音表示系統準 備就緒,可隨時起飛



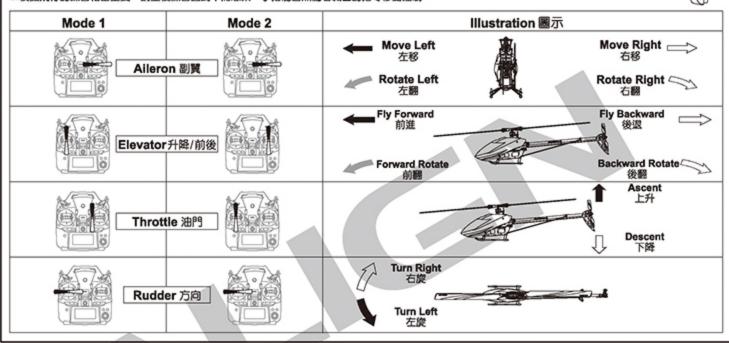
# PLEASE PRACTICE SIMULATION FLIGHT BEFORE REAL FLYING 系行前請事先熟練電腦模擬飛行

A safe and effective practice method is to use the transmitter flying on the computer through simulator software sold on the market. Do a simulation flight until you familiarize your fingers with the movements of the rudders, and keep practicing until the fingers move naturally.

- 1. Place the helicopter in a clear open field ( Make sure the power OFF ) and the tail of helicopter point to yourself.
- 2. Practice to operate the throttle stick (as below illustration) and repeat practicing "Throttle high/low", "Alleron left/right", "Rudder left/right", and "Elevator up/down".
- 3. The simulation flight practice is very important, please keep practicing until the fingers move naturally when you hear operation orders being call out.

在還沒設解直昇機各動作的操控方式前,嚴禁實機飛行,請先進行電腦模擬飛行的練習,一種最有效、最安全的練習方式,就是透過市面販售的模擬軟體,以遙控器在電腦上模擬飛行,熟悉各種方向的操控,並不斷的重複,直到手指可熟練的控制各個動作及方向。

- 將直昇機放在空礦的地方(確認電源為關閉),並將直昇機的機尾對準自己。
- 練習操作遙控器的各搖桿(各動作的操作方式如下圖),並反覆練習油門高/低、副翼左/右、升降舵前/後及方向舵左/右操作方式。
- 3.模擬飛行的練習相當重要,請重複練習直到不需思索,手指能自然隨著喊出的指令移動控制。



#### FLIGHT ADJUSTMENT AND NOTICE 飛行調整與注意

**企**CAUTION

- OCheck if the screws are firmly tightened.
- OCheck if the transmitter and receivers are fully charged.
- ○再次確認→螺絲是否鎖固?○發射器和接收器電池是否足夠。

**企**CAUTION 注意

- · When arriving at the flying field.
- 當抵達飛行場





If there are other radio control aircraft at the field, make sure to check their frequencies and tell them what frequency you are using. Frequency interference can cause your model, or other models to crash and increase the risk of danger. 假使飛行場有其他遙控飛機,請確認他們的頻率,並告知他們您正在使用的頻率,相同的頻率會造成干擾導致失控和大大地增加風險。

#### STARTING AND STOPPING THE MOTOR 啓動和停止馬達

**企**CAUTION 注意

First check to make sure no one else is operating on the same frequency. Then place the throttle stick at lowest position and turn on the transmitter.

首先確認附近沒有其他相同頻率的使用,然後打開發射器將油門搖桿推

- Check the movement
- 動作確認

ON! Step1 First turn on the transmitter.

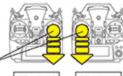


ON! Step2 Connect to the helicopter power 接上直昇機電源



Check if the throttle stick is set at the lowest position.

確認油門搖桿是在最低的位置。



- Are the rudders moving according to the controls?
- ©Follow the transmitter's instruction manual to do a range test.
- 〇方向舵是否随著控制方向移動?
- ○根據發射器說明書進行距離測試。



OFF! Step3 Reverse the above orders to turn off. 關閉電源時請依上述操作動作反執行。

This procedure is best performed on soft surfaces such as grass. The use of rubber skid stopper is recommended on hard surface to prevent vibration feedback from the ground to Gyro, resulting in over-corrections.

將直升機置於柔軟地面上,建議硬地起飛腳架裝上避震整圈。避免升空前腳架與過硬的地面震動太大反饋至機身上的陀螺儀,影響無平衡翼系統升空前過度修正。



**企AUTION** 注意

If swashplate should tilt prior to lift off, do not try to manually trim the swashplate level. This is due to vibration feedback to the Gyro, and will disappear once helicopter lifts off the ground. If manual trim is applied, helicopter will tilt immediately after liftoff.

直昇機難地前,十字盤可能因陀螺儀受震動的反饋,使十字盤有傾斜的情形,此時請勿刻意將十盤修正為水平狀態,此現象只要難地升空時立即解除, 可平理升空:若刻意將十字盤修正為水平時,反而會造成感應器過度修正,一難地即偏往修正方向的危險。

## MAIN ROTOR ADJUSTMENTS 主旋翼雙槳平衡調整

- 1.Before adjusting, apply a red piece of tape on one blade, or paint a red stripe with a marker or paint to identify on blade.
- Raise the throttle stick slowly and stop just before the helicopter lifts-off ground. Look at the spinning blades from the side of the helicopter.
- 3.Look at the path of the rotor carefully. If the two blades rotate in the same path, it does not need to adjustment. If one blade is higher or lower than the other blade, adjust the tracking immediately.
- 網整前先在其中一支主旋翼的翼端,贴上有颜色的贴紙或量上颜色記號,方便雙樂網整辨識。
- 2.慢慢的推起油門搖桿到高點並且停止,在飛機離開地面前,從飛機側邊觀察主旋翼轉動。
- 3.仔細觀察旋翼軌跡(假如兩支旋翼移動都是相同軌跡,則不需要調整;可是如果一支旋翼較高或較低產生"雙樂"的情形時,則必須立刻調整軌跡)。
- a. When rotating, the blade with higher path means the pitch is too big. Please shorten ball link for regular trim.
- b. When rotating, the blade with lower path means the pitch is too small. Please lengthen ball link for regular trim.
- a.旋翼轉動時較高軌跡的主旋翼表示螺距(PITCH)過大,請調短連桿頭修正。
- b.提翼轉動時較低軌節的主旋翼表示螺距(PITCH)過小,請期長連桿頭修正。

**企**CAUTION 注意

Tracking adjustment is very dangerous, so please keep away from the helicopter at a distance of at least 10m.

調整軌跡非常危險,請於距離飛機最少10公尺的距離。

Incorrect tracking may cause vibrations. Please repeat adjusting the tracking to make sure the rotor is correctly aligned. After tracking adjustment, please check the pitch angle is approx. +5~6° when hovering.

不正確的從翼軌跡會導致震動,請不斷重複調整軌跡,使從翼軌跡精準正確。

在調整軌跡後,確認一下Pitch角度在停旋時應為大約+5~6°。

# FLIGHT ADJUSTMENT AND NOTICE 飛行調整與注意





- On not attempt to grab or make contact with the helicopter while the main blades are in motion and keep your eyes away from the helicopter. During take-off, landing, and flight, be sure to keep the helicopter away from all obstacles. Operators must stand at least 10 meters away from the helicopter to avoid injury caused by loose parts due to improper assembly or any unforeseen dangers.
- ◎嚴禁用手抓取運行中的直昇機,並禁止將直昇機對著眼睛,當主旋翼轉動後,或起飛/試飛時,務必遠離障礙物,站立位置必需距離 10公尺以上,避免因人 為組裝不當造成零件脫落,而引發不可預期的財物及人員損傷。

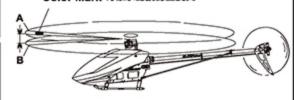
**企**CAUTION 注意

- Make sure that no one or obstructions in the vicinity.
- OFor flying safety, please carefully check if every movement and directions are correct when hovering.
- ◎確認鄭近地區沒有人和障礙物。
- ◎為了飛行安全,您必須先確認停憩時各項操控動作是否正常。

**企**CAUTION 注意

Do not attempt until you have some experiences with the operation of helicopter. 嚴禁無熟揀換控飛行經驗者操控飛行。





## STEP 1 THROTTLE CONTROL PRACTICE 油門控制練習

When the helicopter begins to lift-off the ground, slowly reduce the throttle to bring the helicopter back down. Keep practicing this action untilyou control the throttle smoothly.

○當直昇機開始離地時,慢慢降低油門將飛機降下。 持續練智飛機從地面 上升和下降直到您覺得油門控制很順。







Mode 1

Mode 2

# STEP 2 AILERON AND ELEVATOR CONTROL PRACTICE 副翼和升降控制練習

- Raise the throttle stick slowly.
- 2. Move the helicopter in any direction back, forward, left and right, slowly move the aileron and elevator sticks in the opposite direction to fly back to its original position.
- 1.慢慢升起油門搖桿。
- 2.使直昇機依指示:移動向後/向前/向左/向右,慢慢的反向移動副翼和 升降搖桿並將直昇機開回到原來位置。







Mode 1

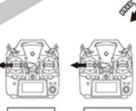
Mode 2

# **企**CAUTION 注意

- ⊚If the nose of the helicopter moves, please lower the throttle stick and land the helicopter. Then move your position diagonally behind the helicopter 10M and continue practicing.
- ⊚If the helicopter flies too far away from you, please land the helicopter and move your position behind 10M and continue practicing.
- ◎當直昇機機頭偏移時,請降低油門並且降落,然後移動自己的位置到直昇機的正後方10公尺再繼續練習。
- ◎假如直昇機飛難你太遠,請先降落直昇機,並到直昇機後10公尺再繼續練習。

## STEP 3 RUDDER CONTROL PRACTICING 方向舵操作練習

- 1.Slowly raise the throttle stick.
- 2. Move the nose of the helicopter to right or left, and then slowly move the rudder stick in the opposite direction to fly back to its original position.
- 1.慢慢升起油門搖桿。
- 2.將直昇機機頭移動左或右,然後慢慢反向移動方向舵搖桿並將直昇機飛回原本位置。





# Mode 1

### STEP 4

After you are familiar with all actions from STEP1 to 3, draw a circle on the ground and practice within the circle to increase your accuracy.

當你覺得 STEP1~3 動作熱悉了,在地上畫圈圈並在這個圈圈的範圍內練習飛 行,以增加你操控的準確度。

OYou can draw a smaller circle when you get more familiar with the actions. ○當你更加習慣操作動作,你可以畫更小的團團



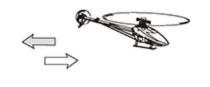
#### STEP 5 DIRECTION CHANGE AND HOVERING PRACTICE 改變直昇機方向和練習停旋

After you are familiar with STEP1 to 4, stand at side of the helicopter and continue practicing STEP1 to 4. Then repeat the STEP1 to 4 by standing right in front of the helicopter.

當你養得STEP1~4動作熟悉了,站在面對直昇機倒達並繼續練習STEP1~4。之後,站在直昇機機頭右達重複步驟練習。









# 18.TROUBLESHOOTING 飛行中狀況排除



	Problem 狀 況	Cause 原 因	Solution 對 策
Blade Tracking 雙槳平衡	Tracking is off 雙榮	Pitch linkage rods are not even Length PITCH連桿長度調整不平均	Adjust length of DFC ball link. 調整DFC連桿頭長度
	Headspeed too low 主旋翼轉速偏低	Excessive Pitch 主旋翼的PITCH偏高	Adjust DFC ball link to reduce pitch by 4 to 5 degrees. Hovering headspeed should be around 1700~1800RPM. 調整DFC連桿頭觸低Pitch約+4~5度 (停懸時主旋翼離為約1700~1800RPM)
Hover		Hovering throttle curve is too low 停懸點油門曲線過低	Increase throttle curve at hovering point on transmitter (around 60%) 調高停懸點油門曲線(約60%)
停懸	Headspeed too high 主旋翼轉速偏高	Not Enough Pitch 主旋翼的PITCH偏低	Adjust DFC ball link to increase pitch by 4 to 5 degrees. Hovering headspeed should be around 1700~1800RPM. 講整DFC連桿頭護高Pitch約+4~5度 (停懸時主旋翼離為約1700~1800RPM)
		Hovering throttle curve is too high 停懸點油門曲線過高	Decrease throttle curve at hovering point on transmitter (around 60%) 調低停懸點油門曲線(約60%)
Rudder Response 尾舵反應	Drifting of tail occurs during hovering, or delay of rudder response when centering rudder stick.	Rudder neutral point improperly set 尾中立點設定不當	Reset rudder neutral point 重設尾中立點
	停懸時尾翼向某一邊偏移,或撥動方向舵並回復到中立點時,尾翼產生延遲,無法 停頓在所控制位置上。	Rudder gyro gain too low 尾舵陀螺簧感度偏低	Increase rudder gyro gain 增加尾紀陀螺镜感度
	Tail oscillates (hunting, or wags) at hover or full throttle 停懸或全油門時尾質左右來回搖擺。	Rudder gyro gain too high 尾舵陀螺簧懸度偏高	Reduce rudder gyro gain 降低尾舵陀螺機感度

If above solution does not resolve your issues, please check with experienced pilots or contact your Align dealer.

※在做完以上調整後,仍然無法改善情況時,應立即停止飛行並向有經驗的飛手諮詢或連絡您的經銷商。

Thank you for purchasing and supporting ALIGN products.

The Align Team is dedicated to you by innovating and developing new RC Helicopters, Multicopters, and FPV Racing Quads to provide a more diversified experience for our customers. Visit our website at www.align.com.tw for the latest news, information, and updates about our extensive line of products for the RC enthusiasts.

# Good Flying!

再次感謝您對亞拓系列商品的喜愛與支持,您的肯定是對我們最大的認同。

亞拓團隊秉持創新研發的精神,開發遙控直昇機/多軸飛行機/穿越機系列 商品,提供給您體驗更多樣化的飛行樂趣。您可以透過下列連結,隨時瞭解 亞拓的最新動態,以及各項訊息分享。

祝福您有一個愉快的飛行體驗。





ALIGN T-REX Helicopter 亞拓遙控直昇機 http://www.align.com.tw/helicopter-en/



ALIGN Multicopter 亞拓多軸飛行機 http://www.align.com.tw/multicopter-en/



ALIGN FPV Racing Quad 亞拓穿越機 http://www.align.com.tw/multicopter-en/mr25/



ALIGN Website 亞拓官網 http://www.align.com.tw



ALIGN Shopping Cart 亞拓購物車 http://shop.align.com.tw/index.php?language=en



ALIGN Quick Finder 亞拓零件快速購 Http://shop.align.com.tw/partfinder.php?language=en



ALIGN FaceBook https://www.facebook.com/Align-Corporation-194493419543/?ref=mf



ALIGN Istagram https://instagram.com/aligncorporation/



ALIGN YouTube
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ALIGN Youku http://i.youku.com/u/UMTQ0NjEwNjczNg==



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# Specifications & Equipment/規格配備:

Length/機身長:1350mm Height/機身高:362mm

Main Blade Length/主旋翼長:700mm

Main Rotor Diameter/主旋翼直徑:1582mm

Tail Rotor Diameter/尾旋翼直徑:281mm

Motor Drive Gear/馬達齒輪:12T

Main Drive Gear/主齒輪:112T

Autorotation Tail Drive Gear/尾驅動主齒:102T

Tail Drive Gear/尾翼傳動齒:23T

Drive Gear Ratio/齒輪傳動比: 9.33:1:4.43 Weight(With Motor)/空機重(含馬達): 3310g

